

# Strongly polynomial algorithm for box-constrained quadratic programs with $H_0$ -matrix

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# Motivation

Liu et al. (2021) investigate the following MIQP

$$\begin{aligned} \min_{x,z} \quad & a^\top z + c^\top x + \frac{1}{2}x^\top Qx \\ \text{s.t.} \quad & \mathbb{R}^n \ni x \perp z \in \{0,1\}^n, \end{aligned}$$

where matrix  $Q$  is sparse positive definite and  $x \perp z$  represents  $x_i z_i = 0 \forall i$ .

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- Decompose  $x^\top Q x = \sum_j x^\top M^j x + x^\top R x$ , where each  $M^j$  is **tridiagonal**

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- At each iteration, solve **unconstrained convex** QPs

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**Question:** What QPs are strongly polynomially solvable? Constraints?

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Consider a convex quadratic program

$$\min_{\ell \leq x \leq u} q^\top x + \frac{1}{2} x^\top M x, \quad (\text{QP})$$

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**Goal:** Solve (QP) in **strongly** polynomial time under the assumption that  $M$  is an  $H_0$ -matrix.

# $H_0$ -matrices

## Comparison matrix

$$M = \begin{bmatrix} m_{11} & m_{12} & m_{13} & \dots \\ m_{12} & m_{22} & m_{23} & \dots \\ m_{13} & m_{23} & m_{33} & \dots \\ \vdots & \vdots & \vdots & m_{nn} \end{bmatrix}$$

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$H_0$ -matrix<sup>1</sup>: A matrix  $M$  is called an  $H_0$ -matrix if  $\bar{M} \geq 0$ .

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- $M$  is an  $H_0$ -matrix  $\Rightarrow M \geq 0$ .
- $M \geq 0$  is tridiagonal  $\Rightarrow M$  is an  $H_0$ -matrix.

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# $H_0$ -matrices

**Notation.** Given a matrix  $M \geq 0$  and  $\alpha, \beta \subseteq [n] := \{1, 2, \dots, n\}$

- submatrix  $M_{\alpha\beta} := (m_{ij})_{i \in \alpha, j \in \beta}$
- the Schur complement of  $M_{\alpha\alpha} > 0$ :  $(M/M_{\alpha\alpha}) := M_{\bar{\alpha}\bar{\alpha}} - M_{\bar{\alpha}\alpha} M_{\alpha\alpha}^{-1} M_{\alpha\bar{\alpha}}$ , where  $\bar{\alpha} = [n] \setminus \alpha$ .

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## Proposition (Operations preserving $H_0$ -property)

Suppose  $M$  and  $N$  are two  $H_0$ -matrices. The following matrices are  $H_0$ -matrices.

- Principle submatrix:  $M_{\alpha\alpha}$  of  $M$ ,  $\alpha \subseteq [n]$
- Schur complement:  $(M/M_{\alpha\alpha})$
- Nonnegative combination:  $\lambda_1 M + \lambda_2 N$  where  $\lambda_1, \lambda_2 \geq 0$

# $H_0$ -matrices

## Irreducibility

- $M$  is *reducible*  $\stackrel{\text{def}}{\iff} M = \begin{bmatrix} M_{\alpha\alpha} & 0 \\ 0 & M_{\beta\beta} \end{bmatrix}$  (up to permutation),  $\alpha, \beta \subset [n]$
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**Key observation:** if  $M$  is reducible,

$$\min_{\ell \leq x \leq u} q^\top x + \frac{1}{2} x^\top M x = \min_{\ell_\alpha \leq x_\alpha \leq u_\alpha} q_\alpha^\top x_\alpha + \frac{1}{2} x_\alpha^\top M_{\alpha\alpha} x_\alpha + \min_{\ell_\beta \leq x_\beta \leq u_\beta} q_\beta^\top x_\beta + \frac{1}{2} x_\beta^\top M_{\beta\beta} x_\beta$$

is separable.

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is separable.  $\Rightarrow$  assume  $M$  is irreducible.

## Parametric principal pivoting algorithm (PPPA)

WLOG, assume  $M$  is an irreducible  $H_0$ -matrix,  $\ell = 0$  and  $u \in \mathbb{R}^n$ . Instead of directly solving

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PPPA traces the solution path of the parametric problem

$$\min_{0 \leq x \leq u} (q + \tau p)^\top x + \frac{1}{2} x^\top M x,$$

where  $p \geq 0$  and  $\exists \tau_0 > 0$  s.t.  $q + \tau_0 p \geq 0$ .

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## Algorithm

- Initialization.  $\alpha = \gamma = \emptyset, \beta = [n]$  and  $\tau = \tau_0 \Rightarrow x^* = 0$

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- Initialization.  $\alpha = \gamma = \emptyset, \beta = [n]$  and  $\tau = \tau_0 \Rightarrow x^* = 0$
- General iteration. Decrease  $\tau$  until  $\tau = 0$ . At each break point, implement diagonal or  $2 \times 2$  pivots and update index sets  $\alpha, \beta, \gamma$   
 $\tau = 0 \Rightarrow x^*$  is optimal for the original QP

# Pivoting analysis

KKT/LCP

$$0 \leq w = q + \tau p + Mx + \lambda \perp x \geq 0$$

$$0 \leq s = u - x \perp \lambda \geq 0$$

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Rearranging:  $\alpha = \{i : 0 < x_i < u_i\}$ ,  $\beta = \{i : x_i = 0\}$ ,  $\gamma = \{i : x_i = u_i\}$ .

$$0 \leq x_\alpha = -\bar{q}_\alpha - \tau \bar{p}_\alpha + \square w_\alpha + \square x_\beta + \square s_\gamma + \square \lambda_\alpha \perp w_\alpha \geq 0$$

$$0 \leq w_\beta = \bar{q}_\beta - \tau \bar{p}_\beta + \square w_\alpha + (M/M_{\alpha\alpha})_{\beta\beta} x_\beta + \square s_\gamma + \square \lambda_\alpha + \lambda_\beta \perp x_\beta \geq 0$$

$$0 \leq \lambda_\gamma = \square - \tau \bar{p}_\gamma + \square w_\alpha + \square x_\beta + \square s_\gamma + \square \lambda_\alpha + w_\gamma \perp s_\gamma \geq 0$$

$$0 \leq s_\alpha = \oplus + \tau \bar{p}_\alpha + \square w_\alpha + \square x_\beta + \square s_\gamma + \square \lambda_\alpha \perp w_\alpha \geq 0$$

$$0 \leq s_\beta = u_\beta - x_\beta \perp \lambda_\beta \geq 0$$

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 0 \leq x_\alpha & = & -\bar{q}_\alpha - \tau \bar{p}_\alpha + \square w_\alpha + \square x_\beta + \square s_\gamma + \square \lambda_\alpha \perp w_\alpha \geq 0 \\
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 0 \leq x_\gamma & = & u_\gamma - s_\gamma \perp w_\gamma \geq 0
 \end{array}$$



Basic variables

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Non-basic variables



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- $H_0$ -property  $\Rightarrow \bar{p}_\alpha \geq 0, \bar{p}_\gamma \geq 0, \oplus \geq 0$ .

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 \end{array}$$

•  $H_0$ -property  $\Rightarrow \bar{p}_\alpha \geq 0, \bar{p}_\gamma \geq 0, \oplus \geq 0$ .

• Ratio test  $\tau_{\text{new}} := \max \left\{ \max_{i \in \alpha} \left\{ -\frac{u_i + \bar{q}_i}{\bar{p}_i} : \bar{p}_i > 0 \right\}, \max_{i \in \beta} \left\{ -\frac{\bar{q}_i}{\bar{p}_i} : \bar{p}_i > 0 \right\}, 0 \right\}$

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•  $H_0$ -property  $\Rightarrow \bar{p}_\alpha \geq 0, \bar{p}_\gamma \geq 0, \oplus \geq 0$ .

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◦  $\bar{i} \in \alpha \rightarrow \alpha_{\text{new}} = \alpha \setminus \{\bar{i}\}, \gamma_{\text{new}} = \gamma \cup \{\bar{i}\}$

# Pivoting analysis

KKT/LCP

$$0 \leq w = q + \tau p + Mx + \lambda \perp x \geq 0$$

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 0 \leq s_\beta = u_\beta & - x_\beta & \perp \lambda_\beta \geq 0 \\
 0 \leq x_\gamma = u_\gamma & - s_\gamma & \perp w_\gamma \geq 0
 \end{array}$$

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 0 \leq s_\beta = u_\beta - x_\beta & \perp & \lambda_\beta \geq 0 \\
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# Pivoting analysis

Note  $\alpha = \{i : 0 < x_i < u_i\}$ ,  $\beta = \{i : x_i = 0\}$ ,  $\gamma = \{i : x_i = u_i\}$

## Type of pivots

$$(1) \alpha_{\text{new}} = \alpha \setminus \{\bar{i}\}, \gamma_{\text{new}} = \gamma \cup \{\bar{i}\}$$

$$(2) \alpha_{\text{new}} = \alpha \cup \{\bar{i}\}, \beta_{\text{new}} = \beta \setminus \{\bar{i}\}$$

$$(3) \beta_{\text{new}} = \beta \setminus \{\bar{i}\}, \gamma_{\text{new}} = \gamma \cup \{\bar{i}\}$$

$$(4) \beta_{\text{new}} = \beta \setminus \{\bar{i}\}, \alpha_{\text{new}} = \alpha \cup \{\bar{i}\} \setminus \{\bar{j}\}, \gamma_{\text{new}} = \gamma \cup \{\bar{j}\}$$

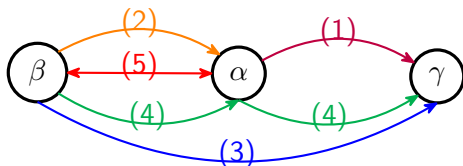
$$(5) \beta_{\text{new}} = \beta \setminus \{\bar{i}\} \cup \{\bar{j}\}, \alpha_{\text{new}} = \alpha \cup \{\bar{i}\} \setminus \{\bar{j}\}$$

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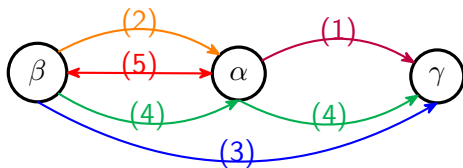


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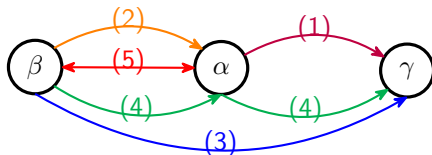


## Theorem (Pang and Han (2021))

*The streamlined PPPA terminates in at most  $2n + 2$  pivots. Consequently, the overall complexity of the PPPA is of order  $\mathcal{O}(n^3)$ .*

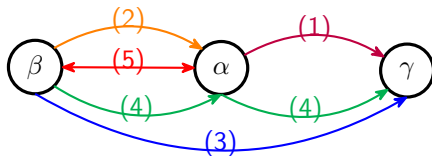


# Iteration complexity of PPPA



Proof.

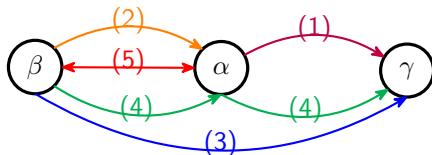
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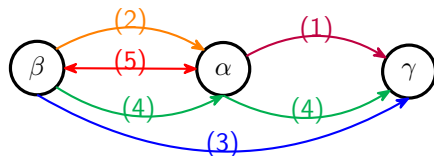
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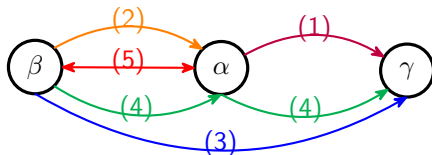
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# Iteration complexity of PPPA



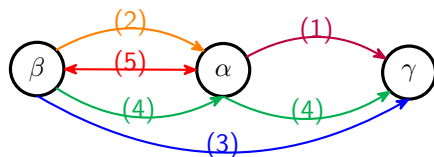
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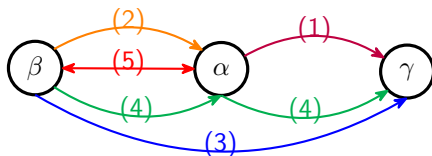
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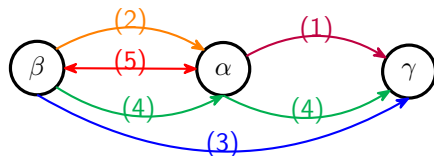
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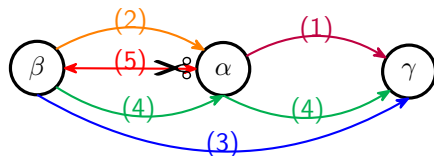
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# Iteration complexity of PPPA



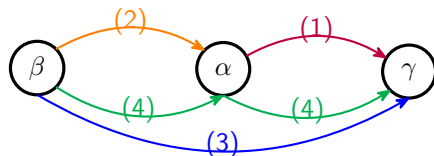
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## More discussion

**Question:** Existence of  $p$  such that  $q + \tau_0 p \geq 0$ ? How to find it?

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### Extension?

- $k$ -weakly quasi-diagonally dominant matrices

# Take home message

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Our paper is available at: <https://arxiv.org/abs/2112.03886>

# Thank You!

# Reference

- Liu, P., Fattahi, S., Gomez, A., and Kucukyavuz, S. (2021). A graph-based decomposition method for convex quadratic optimization with indicators. *[www.optimization-online.org/DB\\_HTML/2021/10/8645.html](http://www.optimization-online.org/DB_HTML/2021/10/8645.html)*.
- Pang, J.-S. and Han, S. (2021). Some strongly polynomially solvable convex quadratic programs with bounded variables. *<https://arxiv.org/abs/2112.03886>*.